Mechanism of hardening and damage initiation in oxygen embrittlement of body-centred-cubic niobium

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1. Introduction

Metals can dissipate a great deal of mechanical energy via plastic deformation, before damage is accumulated inside to cause dramatic change in the component topology, i.e., fracture. While the ultimate damage is in the form of high-aspect-ratio planar cracking [1,], the initial microscopic damage arises from cavitation, i.e., formation of voids and cavities. Gases such as H2, O2, and helium are well known to accelerate the damage initiation in metals and alloys, sometimes in mysterious ways.

Refractory body-centred-cubic (BCC) metals are widely used in nuclear energy, heating elements and rockets [2,3] due to their high melting temperature, excellent strength and creep resistance and good compatibility with liquid metals. However, their mechanical properties rapidly degrade in the presence of dilute impurities such as O, C and N [4–6]. Niobium (Nb), for instance, has appreciable oxygen solubility, and hardens and embrittles at low oxygen levels, decreasing its malleability and fracture toughness and limiting its applications [3–6]. The mechanism that mediate the hardening and embrittlement is the subject of this study.

Oxygen readily enters Nb as impurity in octahedral interstices...
during processing or service [3–6]. The solid solution strengthening effect is traditionally attributed to the attractive interactions between the solute atoms and the dislocation core [11–18]. However, in the following we will show that the two-body interaction between oxygen and screw dislocation (SD) core in Nb is repulsive (also observed for other group V metals and their alloys), and the hardening likely involves unconventional factors. Previous studies of BCC metals indicate that the motion of screw dislocations (SDs) under high stresses can generate excess vacancies [19–24]. Here by “excess”, we mean well beyond the thermal equilibrium concentration. We will show in the following that the presence of oxygen can play a role in the generation and stabilization of vacancies, and these metal-vacancy clusters can interfere with running dislocations to cause hardening and also mediate damage accumulation. This results in accelerated hardening and embrittlement, as discussed below. Because damage develops on multiple time and length scales, beyond the detection ability of a single method, our study combines experimental microstructure analysis underneath the bulk fracture surface, nanoscale mechanical testing, and atomistic computational modeling.

2. Experimental and simulation method

2.1. Preparation of Nb-O solid solution

Heat treatment of nominally pure Nb (with 140 wppm O, 57 wppm N and 88 wppm C) was carried out in a tube furnace, evacuated to a pressure of \( \sim \) 250 Pa and then heated to 1000 °C and held for 1 h, followed by furnace cooling. Oxygen and nitrogen remaining in the furnace were absorbed by the Nb samples. After the heat treatment the sample was mechanically polished to remove the surface oxide. The resultant Nb-O sample contained 1800 wppm O, 120 wppm N and 78 wppm C, as measured using a LECO ONH836 Oxygen/Nitrogen/Hydrogen Elemental Analyzer and a LECO CS844 Carbon/Sulfur analyzer. Similar methods were used to prepare bulk tensile samples and Nb-O single crystal pieces.

2.2. Bulk and micro-scale tensile test

Polycrystalline Nb with average grain size of \( \sim \) 70 \( \mu \)m was cut into dog-bone specimen with the dimensions of 12 mm (length) \( \times \) 5 mm (width) \( \times \) 0.5 mm (thickness), via wire cutting. After cleaning in acetone, the sample was put into the tube furnace for oxygen charging (section 2.1). Bulk tensile tests were conducted at a strain rate of \( 1 \times 10^{-3} \) s\(^{-1} \) on a MTS tensile machine for both Nb and Nb-O polycrystalline samples. In order to check the effect of different oxygen concentration on the tensile properties of Nb, we also performed the oxygen charging at 500 °C, 600 °C, 700 °C and 800 °C for 1 h (Fig. S1). At least five samples were tested for each group.

Single crystal Nb disk was sliced into rectangular plates with dimension of 2 mm \( \times \) 3 mm \( \times \) 0.5 mm by wire cutting. After cleaning in acetone, the samples were put into the tube furnace to produce Nb-O samples. Then the sample was mechanically ground down from one side to the final thickness of \( \sim \) 40 \( \mu \)m while the other surface adhered to the polishing tool to ensure the crystal orientation. The micro-tensile samples were milled by using focused ion beam (FIB). Firstly, a thin plate with 5 \( \mu \)m (length) \( \times \) 2.5 \( \mu \)m (width) \( \times \) 800 nm (thickness) was FIBed from the bulk sample. Then a dog-bone like structure with dimensions of 1 \( \mu \)m (length) \( \times \) 400 nm (width) \( \times \) 800 nm (thickness) was micromachined. Finally, the sample was thinned down to the desired thickness of 150 nm from two sides of the sample by using a low ion beam current to minimize the Ga\(^+\) damage. In-situ mechanical tests were conducted using a Hysitron PI95 TEM PicoIndenter inside a JEOI 2100F TEM (200 KV) under displacement control. The displacement rate was programmed to be 5 nm/s, corresponding to a strain rate of \( \sim \) 5 \( \times \) 10\(^{-3} \) s\(^{-1} \). More than 4 tests were conducted for each loading orientation. The size and loading axis of all the single-crystal Nb-O microsamples were determined in SEM and TEM before each tensile test.

2.3. DFT calculations

We firstly constructed atomic models of dislocation core structure. The introduction of dislocation dipole in a periodic cell is accomplished through application of a continuum linear elastic theory solution for the periodic dislocation dipole array [25]. Lattice constant \( a_0 \) and elastic constants \( C_{11}, C_{12} \) and \( C_{44} \) for Nb, needed to solve the elastic problem of dislocation dipole, are \( a_0 = 3.323 \) Å, \( C_{11} = 247.4 \) GPa, \( C_{12} = 139.0 \) and \( C_{44} = 16.5 \) GPa. The distortion field is then chosen to minimize the total elastic energy subject to the topological constraints imposed by the dislocations. The predicted displacement at the atomic positions is obtained by a line integral starting from a reference coordinate. In this work, the \( \langle 111 \rangle \) screw dislocation dipole is considered. The dipole is inserted into a 405 atom supercell with three layers along \( \langle 111 \rangle \) direction. Subsequently, a vacancy and oxygen interstitial were inserted around dislocation core.

We then carried out the density functional theory (DFT) calculations to obtain stable configuration of dislocation core around an oxygen interstitial and a vacancy, and investigated the interaction energy between these defects. The DFT calculations were implemented using the Vienna Ab initio simulation package (VASP) [26,27] with the Perdew–Burke–Ernzerhof formulation of the generalized gradient approximation to the exchange–correlation density functional [28]. The plane-wave energy cutoff was set at 400 eV. The Brillouin-zone k-point samplings were chosen using the Monkhorst–Pack algorithm [29]. A \( 1 \times 1 \times 6 \) k-point sampling was used for all calculations. Convergence of self-consistent field calculations was determined when energy difference becomes below \( 10^{-6} \) eV. The fully relaxed configurations were obtained by the conjugate gradient method that terminated the search when force on all the atoms was reduced to less than 0.01 eV/Å. The transition state during dislocation motion was calculated by nudged elastic band (NEB) method [30]. Nine intermediate replica images were used for NEB simulation and the convergence condition of forces were less than 0.02–0.025 eV/Å. Atomic model used in the present study was visualized by ATOMYEYE [31] and VESTA [32] software.

2.4. MD simulations

All the MD simulations are based on our newly developed embedded atom method (EAM) potential for the Nb-O system. The details of EAM potential development and validation will be presented elsewhere. We considered the \( \langle 111 \rangle \) screw dislocation which, on average, glides on the \( \{112\} \) plane at 300 K, as predicted by the new EAM potential. For the general purpose of simulating screw dislocation motion, we used a simulation box with dimensions of 23 nm \( \times \) 18 nm \( \times \) 61 nm along X[010], Y[121] and Z [111], respectively. Periodic boundary conditions were applied in the dislocation motion direction (i.e., X[010]) while free surfaces were used in the other directions. Screw dislocations were introduced according to the anisotropic elasticity theory of dislocation [33] and the corresponding displacement was solved using the Atomsk package [34]. For simulations involving various point defects, we introduced the point defects in a random way. For example, vacancies were introduced by randomly removing atoms and oxygen interstitials were introduced on randomly chosen...
octahedral sites (both DFT and the EAM potential predict that the octahedral O interstitial is more stable than the tetrahedral O interstitial). In addition to the random sites, V-O defects (i.e., the binding of one O and one vacancy) were also introduced with random orientations regarding the slip plane. All samples were first relaxed at 300 K for 100 ps and then shear was applied either under a constant strain-rate of $5 \times 10^{-3}$ s$^{-1}$ or constant shear stresses to drive the motion of screw dislocation. An integration time step of 1 fs was used to update atomic positions. All simulations were carried out using the LAMMPS package [35] and analyzed by common neighbour analysis [36,37] as implemented in the OVITO package [38].

3. Results

3.1. Solute oxygen induced brittle fracture in tensile test

The experimental samples start with two types of polycrystalline Nb: one is nominally pure Nb with 140 wppm oxygen (hereafter referred to as “Nb”), and the other is Nb with oxygen purposely added to 1800 wppm (i.e., $\sim$1 at% O, hereafter referred to as “Nb-O”; prepared by heating the nominally pure Nb at 1000 °C for 1 h in 250 Pa Ar). Fig. 1(a) demonstrates the observation of oxygen embrittlement, using centimeter-scale bulk tensile tests on these two types of samples. As shown in Fig. 1(a), bulk Nb shows a yield point at $\sim$150 MPa, then strain-hardens slowly to a peak stress of $\sim$200 MPa, and fractures at a total strain of 50%. The inset in Fig. 1(a) shows the final fracture in a shear mode of this ductile Nb sample. In contrast, bulk Nb-O shows more than double the strength, but failed catastrophically, rupturing into several pieces, indicating that the $\sim$1 at% of oxygen solutes drastically hardens and embrittles macroscale Nb. With increasing oxygen concentration, hardening and degradation of ductility becomes more severe in bulk Nb (Fig. S1).

The deformation microstructure underneath the fracture plane (in FIB lift-out samples) was compared for Nb versus Nb-O. In the case of Nb, high density of dislocations and cavities of various sizes are observed a few microns away from the fracture plane, as shown in Fig. S2, indicating profuse plasticity and gradual damage accumulation during necking. In contrast, the Nb-O exhibits transgranular quasi-brittle fracture features at lengthscale of 100 $\mu$m, as displayed in Fig. 1(b). Mainly three types of deformation microstructures are formed in local regions near the fracture surface in Nb-O: deformation twins (Fig. 1(c)), slip bands (Fig. 1(g)), and micro-cracks of different aspect ratios beneath the fracture surface (Figs. S3(b) and (c)). These observations indicate that plasticity is more difficult and localized in Nb-O, preceding the crack nucleation and quasi-brittle failure [39,40]. It is difficult to imagine how a metal can separate atomistically at lengthscale of 10$^3$ nm without coalescence of cavities, but the lengthscale and timescale of such cavity dynamics in bulk Nb-O could be so much smaller and faster than Nb that they are well beyond the range that can be captured in experiments. In other words, there can be a severe space-time “contraction” of the damage progression process. Further microstructural characterizations using Atom Probe Tomography (APT) reconstruction and high-resolution TEM did not detect metal oxides inside the Nb-O (Fig. S4), and the Nb-O atomic distance distribution matches that of a random solid solution (Fig. 1(h) and (i)), thus the embrittlement is mainly caused by the homogeneous distribution of oxygen as solutes.

3.2. Abnormal strain hardening and shear localization

Because damage mechanics is controlled by extreme-value statistics (i.e. the largest flaw is by far the most damaging) [41], we switched to tensile testing of submicron-sized samples inside an SEM. In this case the total elastic energy is tiny and the lengthscale progression of the plasticity-damage conjugate localization process is interrupted, allowing us to record the flow, hardening and damage accumulation in a small deformation volume. Fig. 2(a) shows a typical example of tensile test of Nb and Nb-O single crystals with [101] orientation. The behavior of Nb is expected: compared with the bulk sample the submicron sample exhibits higher yield strength and frequent strain bursts due to dislocation avalanches [42,43], as shown in Fig. 2(a). Similar to bulk Nb-O, dramatic differences were observed on the stress-strain curve once Nb is oxygenated (Movie S1). The Nb-O single crystal is not only much stronger (yield strength $\sim$1.35 GPa), but also exhibits a rapid strain hardening stage with a near-constant strain hardening rate ($\Theta$) ($\Theta$ = $\partial$e$/\partial$ε where $\sigma$ is the stress and $e$ is the strain) as high as 12 GPa ($\Theta$ = 0.32, where $\mu$ = 37.5 GPa is the shear modulus of Nb), far exceeding that for normal metals ($\Theta$ < 0.1) [44–46]. Significant strain hardening was also observed in bulk Nb containing different levels of oxygen (Figs. S1(a) and (b)). After the dramatic strain hardening to peak stress of $\sim$1.9 GPa, pronounced stress drop kicks in as the deformation starts to localize, all the way until the eventual fracture. Similar differences in stress-strain curves and significant strain hardening were also observed for other crystal orientations (Fig. S5).

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The small sample size, while known to have significant effect on strength [47], is the same for Nb and Nb-O. Therefore, these prominent differences in the single-crystal plasticity and damage can be attributed to the $\sim$1 at% oxygen solute. Although the overall stress and plastic strain levels are elevated in micro-samples, the local damage initiation process should bear similarity to that of bulk samples. This is because a) the local stress in bulk Nb-O may be close to that in micro-samples due to stress concentration (e.g., 1 GPa local stress can be reached for a minimum stress concentration factor of 3 and a yield stress of 350 MPa in Fig. 1(a)); b) similar stress-strain curves should be expected for micro-scale Nb and Nb-O if high stress is the only cause of damage initiation, which obviously contradicts the experiments; and c) severe localized plasticity was indeed observed for both bulk samples (Fig. 1(g) and Fig. S3) and micro-samples (Fig. 2(d), Figs. S7 and S8).

Unusually large $\Theta$ is observed in both bulk and submicron Nb-O samples (Fig. 2(a) and Fig. S1). But the submicron tests give us better temporal control and access to the deformed and/or damaged volume. In order to capture the dislocation structures evolution during the stage of drastic strain hardening, we interrupted the test at the plastic strain of 5% on a [101] submicron-sized Nb-O single crystal (Fig. S6 and Movie S2). A snapshot is shown in Fig. 2(b). As can be seen, very-high-density dislocation substructures are stored in the small-volume sample during the hardening stage, consistent with the extraordinary strain hardening rate observed (Fig. 2(a) and Fig. S5). Such significant dislocation trapping and storage is in contrast to submicron pure metals where most dislocations can be effectively driven out the tiny sample volume [48]. These results indicate that oxygen is effective in pinning down and assisting the storage of dislocations, counteracting the surface sinks.

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Different strain localization and fracture behaviors are also observed for submicron Nb and Nb-O samples. The fracture in [101] oriented Nb-O is clearly due to the intense localized slip in a very narrow channel (along both [110] and [112] planes in Fig. S7); incipient crack nucleates at the sample edge intersecting with the localized slip zone, causing catastrophic cleavage fracture along the
Fig. 1. Bulk tensile test and microstructure under fracture surface. (a) Engineering stress-strain curve of bulk tensile test for Nb (green curve) and Nb-O (red curve). Insets are images of bulk Nb-O and Nb samples after fracture. (b) A typical SEM image of transgranular semi-cleavage fracture surface of the Nb-O sample. (c) A dark field TEM image of deformation twin beneath the ridges of Nb-O fracture surface. The zone axis is [1\bar{1}0]. (d) Low-magnification SEM image of the crack tip. (e) High-magnification SEM image of ribbon structures formed near the crack tip in the boxed region in (d). (f) A SEM image showing the position on the fracture surface for cutting the TEM thin foil for further characterization. (g) A bright-field TEM image of the microstructure beneath the ribbon morphology. Distinct localized slip on (110) planes is observed beneath the surface steps, which are indicated by arrows. (h) and (i) Three-dimensional APT reconstruction of the Nb-O sample, showing homogeneous distribution of O in Nb. (For interpretation of the references to color in this figure legend, the reader is referred to the Web version of this article.)

We now look into the atomistic origin of the observations above, focusing on the mechanisms of rapid strain hardening and damage accumulation, which can be technically defined as the loss of total metal-metal coordination (TMMC) in a volume. DFT calculations are employed to obtain the two-body and three-body interaction energies among SD, vacancy (V) and oxygen (O) (Fig. 3 and Fig. S9). The two-body interaction energies were calculated for V-O, SD-V, and SD-O. As summarized in Fig. 3(b) and Table 1, the strongest interaction between a vacancy and an oxygen in BCC Nb was found to be $-0.80 \text{ eV}$, associated with the first nearest-neighbour (NN) configuration (Fig. 3(a) and Fig. S9), indicating a strong V-O attraction. For interactions between V and SD, attractive interactions were found: the interaction energies for the first, second and third NN configurations (Fig. S9) are $-0.51 \text{ eV}$, $-0.49 \text{ eV}$ and $-0.051 \text{ eV}$, respectively. However, this attractive interaction between a vacancy and a SD decays rapidly with distance. Oxygen, on the other hand, has repulsive interaction with the SD: when an O was placed at the nth NN from the dislocation core, strong repulsive interactions were found up to the fourth NN (see Fig. S9), e.g., the interaction energies for the first, second, third and fourth NN configurations are all positive, 0.34 eV, 0.1 eV, 0.55 eV and 0.54 eV, respectively. In contrast, the three-body interactions between V-O pair and SD core (Fig. 3(b) and Fig. S9) are extremely attractive (Table 2), with an interaction energy of at least $-1.0 \text{ eV}$, which exceeds by far the V-SD interaction. In other words, it is the V-O-SD three-body interaction that stands out, potentially responsible for trapping SDs. Note that the interaction energies between solute and a screw dislocation include both the elastic interaction and chemical effects [45].

The resultant dramatic hindrance on SD motion is further demonstrated by nudged elastic band (NEB) calculations [50] on the migration energy of a SD in pure Nb and Nb-O. As shown in Fig. 3(c) and (d), the energy barrier for dislocation motion around the V-O pair is almost an order of magnitude higher than that without V-O pair (0.169 eV/b versus 0.018 eV/b). In addition, we also evaluated the interactions between $V_{m}O_{n}$ cluster and SD, as shown in Fig. S10: the formation energy of $V_{m}O_{n}$ is reduced significantly when attached to SD. These pronounced three-body interactions and vacancy cluster stabilization may play an...
important role in damage initiation of oxygen embrittlement; note that the atomistic processes are beyond the detection limits of current experimental techniques.

4.2. Oxygen solutes enhance cross kink formation and hardening

Rapid hardening arising from the V-O-SD attractive interaction and the formation of oxygen stabilized vacancy clusters require the availability of vacancies. One vacancy introduces $\Delta TMMC = -8$, and is the smallest form of damage. It is well-known that excess vacancies can be created in metals with the injection of plastic work [30,51]. We illustrate next how excess vacancies are efficiently generated and stabilized in the wake of passing SDs. To this end, MD simulations are carried out. Previous experiments and MD studies [19–24] have shown that superabundant vacancies and interstitials can be created in pure BCC metals by pinching off cross-kinks on SDs moving under very high stresses (also see Fig. S11 in the case of pure Nb). The relatively high stress level for SD to generate point-defect in pure Nb is due to the fact that an elevated kink-pair nucleation rate is required for forming and pinching off cross-kinks. Considering the relatively low stress level in our experiments, that specific mechanism is unlikely to play a dominant role here. However, a new mechanism emerges due to the presence of oxygen. We found that when a SD passes through the O interstitials, the medium-ranged repulsive interactions between the SD and randomly distributed O interstitials constantly twist local dislocation segments onto different glide planes to form cross-kinks, as schematically illustrated in Fig. 4(a). When a SD moves ($t_0$) through the repulsive random force field (RFF) imposed by O, local segments can be subjected to net forces with different directions ($t_1$), therefore pushing the local segments onto different glide planes to form cross-kinks ($t_2$). The local segments then continue to bypass the O solutes via nucleating extra cross-kinks ($t_3$) that lead the entire dislocation line back to the original glide plane, forming a point defect ($t_4$). Such a process to “pinch off” point defects is similar to that described in Ref. [20]; however, the required high cross-kink nucleation rate is now driven by the O-RFF, rather than the ultra-high applied stress.

To demonstrate the effects of RFF on gliding SDs, we carried out MD simulations on a single $1/2<111>$ SD in samples of pure Nb, Nb-O(0.5 at%) and Nb-O(1.0 at%). The introduced SD glides on a $\{112\}$ plane (the predicted glide plane of the current potential at 300 K).

![Fig. 2. Nanomechanical tensile tests of submicron-sized Nb and Nb-O inside TEM.](image-url)
and periodic boundary conditions are only applied along the motion direction. All three samples are sheared with a constant strain rate $5 \times 10^7 \text{s}^{-1}$ at 300 K. As shown in Fig. 4(b), the yielding stress and flow stresses of oxygenated samples are obviously higher than that of the pure Nb sample, suggesting significant hardening effects. Such hardening is due to two factors: a) the RFF induces cross-kinks, requiring higher pinch-off stress (as indicated by the higher yielding point) to maintain SD motion; b) the formation of vacancy-oxygen complex also traps SD during motion. Fig. 4(c) further compares the SD configurations at a shear strain of ~7.3% for samples of pure Nb and Nb-O(0.5 at%), respectively. As expected, the SD glides smoothly in pure Nb sample (the upper panel of Fig. 4(c)) and leaves no point defects behind. In contrast, the SD gliding in the sample of Nb-O(0.5 at%) generates various defects such as V-O cluster (marked by yellow atoms), vacancies (marked by blue atoms) and vacancy tube (marked by magenta atoms). Note that the stress levels to generate these various defects in Nb-O samples are much lower (~0.5 GPa, Fig. 4(b)) than that required in pure Nb (~2.5 GPa, see Fig. S11), easily reachable in bulk- and micro-scale experiments. These results emphasize the important role played by the O-RFF in both hardening and defect generation.

The RFF-enhanced cross-kink and point defect formation are expected to work for SDS gliding on both {110} and {112} planes, as on both types of planes, neither crystallographic restrictions on cross-kink formation nor significant anisotropy of RFF has been found. To demonstrate this, the enhanced cross-kink formation process in action has been studied in detail. We have conducted a finite-temperature ($T = 300$ K) MD simulation of a screw dislocation (Fig. 5(a)-(c), dislocation core atoms are colored according to their positions along the normal direction of the slip plane, i.e., blue/red atoms are below/above the original slip plane) moving through 0.5 at.% O (easier visualization than the more O-crowded 1 at.% O case) interstitials (smaller blue atoms). As can be seen, once the screw dislocation is subjected to constant rate ($5 \times 10^7 \text{s}^{-1}$) shear, local segments readily glide onto different slip planes and form cross-kinks (marked using the blue arrows). Such enhanced formation of cross-kinks has not been observed in O-free sample sheared under the same conditions, indicating that O interstitials and the associated RFF are the direct cause of the prominent cross-kink formation. To further verify that the O-RFF can indeed facilitate cross-kink formation, Fig. 5(d) introduces a screw dislocation in a better-defined O force field where the dislocation line is divided into two equal segments and then subjected to opposite repulsive forces imposed by O atoms. In this set-up, the left segment tends to glide downward and the right segment tends to glide upward. Cross-kinks are then expected to form at the joint of the two segments. As seen in Fig. 5(e), after the initial energy

Table 1
Two-body interaction energies (including both elastic and chemical effects) among V, O and SD in the unit of eV.

<table>
<thead>
<tr>
<th></th>
<th>0th NN</th>
<th>1st NN</th>
<th>2nd NN</th>
<th>3rd NN</th>
<th>4th NN</th>
</tr>
</thead>
<tbody>
<tr>
<td>V-O</td>
<td>0.044a</td>
<td>-0.80</td>
<td>-0.17</td>
<td>0.13</td>
<td>-</td>
</tr>
<tr>
<td>SD-V</td>
<td>-</td>
<td>-0.51</td>
<td>-0.49</td>
<td>-0.05</td>
<td>-</td>
</tr>
<tr>
<td>SD-O</td>
<td>1.75b</td>
<td>0.34</td>
<td>0.10</td>
<td>0.58</td>
<td>0.54</td>
</tr>
</tbody>
</table>

a Equivalent to the formation energy of substitutional O.
b Equivalent to an unstable site at the center of SD core.

Table 2
Three-body interaction energies (including both elastic and chemical effects) between V-O pair and SD in the unit of eV.

<table>
<thead>
<tr>
<th></th>
<th>O (site1)</th>
<th>O (site2)</th>
<th>O (site3)</th>
</tr>
</thead>
<tbody>
<tr>
<td>V (site0)</td>
<td>-0.94</td>
<td>-0.97</td>
<td>-0.97</td>
</tr>
<tr>
<td>V (site1)</td>
<td>-0.95</td>
<td>-1.02</td>
<td>-1.04</td>
</tr>
</tbody>
</table>

Fig. 3. First-principles calculations of the interaction energy among vacancy, oxygen interstitial and screw dislocation core and the migration energy barrier for screw dislocation in Nb-O. (a) The atomic model of a SD core with a vacancy after inserting an oxygen interstitial. (b) The interaction energy for vacancy-oxygen, vacancy-SD, SD-oxygen and the three-body interaction. (c) The atomic model for the migration motion of SD around a vacancy-oxygen complex. (d) The migration energy of a SD in Nb with and without vacancy-oxygen complex.
minimization and MD relaxation at 300 K for 10 ps, the left segment and the right segment indeed relocate their positions, i.e., while some local regions of the left segment move slightly downward, the right segment moves entirely upward (the atom colors are mostly red), forming a cross-kink at the joint (indicated by the arrow). Upon shear straining (Fig. 5(f)), the left and right segments glide further downward and upward, respectively, piling up even more cross-kinks at the joint. This set of simulation thus clearly demonstrates that O-RFF enables easy cross-kink formation.

4.3. Atomistic processes of point defect generation

Now let us take a closer look at the atomistic processes of point defect generation, biased stabilization of vacancy and cavity formation. The ensuing pinch-off of cross-kinks generates not only copious vacancies, but also self-interstitials (SI). Fig. 6(a)–(c) show a typical process of ‘instant’ pinch-off, forming a VO-SI pair. As seen, after encountering cross-kinks get pinned by each other in Fig. 6(a), a vacancy immediately takes shape near an O interstitial (Fig. 6(b)). Meanwhile, more cross-kinks are aggregating at the left SI site (Fig. 6(b)). Afterwards both the vacancy and SI are completely pinched off and the vacancy is captured by an O interstitial, creating a VO-SI pair. Such ‘instant’ pinch-off process not only provides efficient vacancy source but also a strongly coupled generation-stabilization mechanism of vacancies in the O-RFF (otherwise both O and V need to diffuse on a much longer timescale). An even more efficient way to generate various defects is the ‘delayed’ pinch-off process (Fig. 6(d)–(f)). A SI pinning site is formed when cross-kinks block each other and result in a short SI dipole (Fig. 6(d)). However, this SI dipole is not immediately pinched off; instead, a much longer SI dipole (Fig. 6(e)) is dragged out. Eventually, the long SI dipole is pinched off and broken into two separate prismatic loops (Fig. 6(f)). While the SD drags out a long SI dipole on the right side, many individual vacancies and V-O complexes are also formed on the left side (Fig. 6(e)–(f)) via the ‘instant’ pinch-off process. This is because the cross-kinks are often nucleated in pairs; for the halves generating SI the other halves are prone to be instantly pinched off to form vacancies, as vacancy-type point defect is much easier to be closed up. Note that free surfaces do not artificially act as kink sources, as indicated by the slight bow-out shape of the dislocation line shown in (c). (For interpretation of the references to color in this figure legend, the reader is referred to the Web version of this article.)

Fig. 4. Random force field (RFF) imposed by O on screw dislocation leads to enhanced cross-kink and point defects formation and hardening. (a) Schematic of cross-kink and point defect formation due to repulsive force field imposed by oxygen solutes. Red arrows indicate the directions of the local repulsive forces. Dislocation segments and kinks are represented by blue lines. The slip plane ([112] plane in this case) is rendered in yellow. (b) Shear stress vs. shear strain curves for a single SD gliding in samples of pure Nb, Nb-O(0.5 at.%) and Nb-O(1.0 at.%), respectively. (c) Comparison of SD configurations in pure Nb (upper panel) and Nb-O(0.5 at.%) (lower panel) at a shear strain of ~7.3%. Arrows indicate the motion direction of SD. Vacancies, V-O clusters and vacancy tube are marked by blue atoms, yellow atoms and magenta atoms, respectively. SD and free surfaces are marked by green atoms. The SD length is 57 nm. Note that our EAM potential was fitted to the total interactions between solute and screw dislocation from ab initio calculations, thus capturing both the elastic and chemical effects. Periodic boundary conditions are only applied in the dislocation motion direction. Free surfaces along the dislocation line direction are adopted to be consistent with grain boundaries and free surfaces in lab experiments and to eliminate artificial cross-kinks resulting from using periodic boundary conditions. Note that free surfaces do not artificially act as kink sources, as indicated by the slight bow-out shape of the dislocation line shown in (c). (For interpretation of the references to color in this figure legend, the reader is referred to the Web version of this article.)
'saturated' with cross-kinks created due to external RFF, copious defects of various types are precipitated out in its wake so as to maintain the dislocation glide.

4.4. The stability of newly formed SI, V and V-O complex

Notably, the SI, V and V-O complex have very different stability, upon hitting by the passing SD. This creates a sink bias that promotes the accumulation of vacancies (-D_TMMC) and damage.

Fig. 7(a) shows a SD passing through various dynamically formed defects. The SD first reacts with a SI cluster (Fig. 7(b)-(c)); the SI cluster is decomposed into multiple cross-kinks that immediately run away (Fig. 7(c)). In other words, SI can be effectively annealed out to become extra plane of perfect crystal, and new vacancies and V-O complexes are created (Fig. 7(b)-e). Similarly, vacancies and weakly bound V-O complexes (O is not in the 1st NN of V) can also be decomposed by moving SD. As shown in Fig. 7(c)-(f), when the SD passes through weakly bound V-O complexes and vacancies, it decomposes all the vacancies into cross-kinks and some of them 'precipitate out' as new vacancies on the left side when meeting other appropriate cross-kinks. In contrast, all V-O complexes, except for those weakly bound, stay put after the SD passes though (see Fig. 7(f)).

To further confirm the stability of V-O complexes, we performed separate simulations to drive a SD through an array of V-O complexes. As seen in Fig. S12 and Movie S5, almost all the V-O complexes remain stable inside the grain, and some of them even grow into bigger nano-cavities by absorbing excess vacancies created during SD motion. This set of simulation results thus demonstrate very different relative stabilities for SI and V-O complexes, i.e., with the passing of SDs, SI are effectively annealed out but V-O complexes can largely remain inside the crystal, creating a strong bias to accumulate nano-cavity damage with larger and larger -D_TMMC, both in the average and the extreme-value statistics [41] senses. Such interplay between SDs and the dynamically formed defects (V-O complexes, vacancies and SI) highlight an auto-catalyzed, self-reinforced damage accumulation process. Note that all the above processes occur on the displacive timescale rather than on the longer diffusive timescale, therefore effectively pre-empting the diffusive annealing of damage. The stress level required for this mechanism to operate is not high and falls within the range of our experiments.
Fig. 7. Self-interstitial, vacancy and V-O complex exhibit different stability when hit by passing screw dislocation. (a) A screw dislocation is gliding towards various dynamically formed defects. (b–c) The screw dislocation decomposes the first SI cluster into cross-kinks and form three new V-O complexes and a vacancy. The inset in (c) shows the structure of a weakly bound V-O complex (highlighted by the dashed enclosure) that is decomposed later. (d) The screw dislocation decomposes a second SI cluster, a weakly bound V-O complex and a vacancy into cross-kinks. The inset of (d) shows the structure of another weakly bound V-O complex (V_{2O}, highlighted by the red dashed enclosure), which is decomposed into cross-kinks later. (e) New vacancies are formed on the left-side. The inset of (e) shows a V-O complex (highlighted by the red dashed rectangle) that remains stable after the screw dislocation passes through in (f). (f) The screw dislocation passes through more V-O complexes and most of them remain stable. The inset of (f) shows the vacancy clusters (V_s, the red dashed rectangle) formed by relocating the vacancies on the right-side in (c) to (e). (For interpretation of the references to color in this figure legend, the reader is referred to the Web version of this article.)

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4.5. Damage accumulation to form nano-cavities

Our MD simulations have captured how nano-cavities are nucleated and efficiently grown athermally, even on very short timescale and small lengthscale. As shown in Fig. 8(a) and (b), following the ‘delayed’ pinch-off mechanism, a long V-O tube takes shape as a SD passes through, together with a continuously increasing population of V-O complexes as well as vacancies. Such a much-delayed pinch-off of vacancy debris is generally observed in the modified RFF after some passes of SDs. This is because prismatic loops of vacancy type are generally much easier to be closed up and detached from the SD when compared to SI prismatic loops [20]. However, with increasing passes of SDs in a modified RFF, the probability to create a much more stable atomic jog (e.g., with larger jog height) would be increased such that the ‘instant’ pinch-off forming individual vacancies becomes less likely. The long V-O tube formed generally is quite stable as O are readily available along the tube to stabilize it from collapsing. As a result, later SDs continue the same action along the existing vacancy tube, quickly expanding the cross-section area (the diameter of the tube is ~2 nm in Fig. 8(d)) of the V-O tube (Fig. 8(c)-(d)). The individual SD segments can continue to form new V-O tubes near the existing one in a similar way (Fig. 8(d)-(e)). In Fig. 8(e), we take the snapshot after nine passes of SDs to illustrate the large prolate nano-cavities (with sizes from 1 nm to 2 nm) being formed. Fig. 8(f) depicts the cross-section indicated by the two parallel dashed lines in Fig. 8(e) on the tube-shaped nano-cavities, showing a hollow and sheared shape. Fig. 8(g) shows a V-O clusters where vacancies are interconnected and stabilized by O interstitials. With more and more V-O tubes formed near each other, these nano-cavities would eventually coalesce and result in crack initiation (Fig. 2(d) and (e)), in an expected prolate-to-oblate transition, a process driven by elasticity. Detailed damage accumulation process can be found in Movie S6 (0.5 at.% O sample) and Movie S7 (1.0 at.% O sample). There appears to be also “displacive accumulation” of point defects and defect clusters that can happen even at zero temperature, expedited by stress-driven displacive events, unlike typical thermally activated diffusional processes [52,53]. This additional athermal mode of rapid accumulation of damage will be analyzed elsewhere.

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4.6. Oxygen induced embrittlement in Nb

To recapitulate, we have used DFT and MD simulations to discover the mechanisms for hardening and damage initiation on atomic scale. They are not resolvable due to limited temporal and spatial resolution in laboratory experiments. We have uncovered the following “vicious cycle” for damage initiation. The initial repulsive RFF imposed by O interstitials on SDs facilitates the formation of cross-kinks [20] to generate excess defects such as vacancies, V-O complexes and SIs at a low stress (Figs. 4 and 6). Upon the passing of ensuing SDs, SIs can be easily annealed out while most of the V-O complexes remain stable, creating a strong bias for damage accumulation. Nano-cavities are then efficiently formed by the ‘delayed pinch-off’ of vacancy dipoles and stabilized by oxygen interstitials. This displacive damage accumulation mechanism is rapid and highly efficient. These dynamically formed V-O complexes are obstacles for SDs and their average spacing is very small (<2 nm), and are much more difficult to be “picked up” by the dislocations compared to the SI clusters.

In this context, the dynamically formed oxygen-vacancy complexes pin the moving dislocation. As such, the flow stress (τ) needed for dislocation to bow out in between the neighboring roadblocks is,

$$\tau = \frac{\alpha \mu b}{\lambda}$$

(1)

where α is a constant in the range of 0.1–0.5, μ = 37.5 GPa is the shear modulus of Nb, b is the Burgers vector of dislocation, and λ is the average spacing between oxygen-vacancy complexes that each sets a pinning site for the mobile dislocations. The mean free path of the dislocation, L, which is controlled by λ, results in a shear strain of

$$\gamma = \rho b L = b \times \frac{1}{\lambda^2} \times \lambda = \frac{b}{\lambda}$$

(2)
where $\rho$ is the dislocation density. Therefore, the strain hardening rate can be estimated as [46],

$$\Theta = \frac{d\tau}{d\gamma} = \frac{d_1 \mu b}{dv} = a \mu$$  \hspace{1cm} (3)

In the extreme case of a homogeneous distribution of the 1 at.\% of oxygen atoms in the Nb lattice, their average spacing would be as small as $\sim 1.22$ nm. Therefore the dynamically formed oxygen-vacancy complexes would make the dislocation glide very difficult, leading to an unprecedented strain hardening rate. Eq. (3) predicts a strain hardening rate of the range of 3.75–18.75 GPa. This magnitude is consistent with the experimental observation displayed in Fig. 2 and Fig. S5. On top of the isotropic strain hardening, a significant kinematic hardening was also observed in Nb-O due to the dynamic formation of oxygen-vacancy complexes, as shown in Fig. S6.

Various dynamically formed defects further randomize the local force field on ensuing SDs, setting the stage for the generation of even more debris, resulting in a self-reinforcing loop. In terms of initiating damage, the biased vacancy accumulation at V-O promotes the seed to form nano-cavities that can coalesce (Fig. 2) and initiate damage, the biased vacancy accumulation at V-O prefiguring damage localization, i.e. inequalities of plastic strain and deformation (right after the peak hardening is reached) is extreme and erratic (Fig. 1). If the whole sample however is just of micron-size or smaller, then the total stored elastic energy is smaller and this natural lengthscale progression of the plasticity-damage conjugate localization process is interrupted, and Nb-O appears to strain harden faster and ‘tougher’ than Nb, as the areas under the stress-strain curves in Fig. S1(a) and S5 would suggest.

The damage initiation mechanisms demonstrated above are expected to be general in BCC metals. First, the RFF mechanism underlyng the enhanced cross-kink and point defects generation is expected to be applicable under a wide range of strain rates, from typical laboratory experiment to MD simulations. We carried out extra MD simulations under constant shear stresses to estimate the lower bound of the working range for the random force field. At 300K and a shear stress as low as 0.3 GPa (further lower stress levels would need significantly longer time to observe dislocation motion, which is beyond typical MD simulation timescale), we still observe point defects generation in the Nb-O sample (see Fig. S11(c)). In contrast, point defects are generated in pure Nb sample only when the shear stress is greater than $\sim$2.5 GPa (see Fig. S11(a)-(b)). This suggests that the RFF lowers the required shear stress for point defects formation by at least one order of magnitude for the current simulations setup. According to our MD simulations, the mobility of the screw dislocation, at 0.3 GPa in the Nb-O sample, is on the order of $10^{-1}$ m/s. Then the corresponding strain rate can be approximated using the Orowan equation, $\dot{\gamma} = \frac{\mu b}{\tau}$, where $\mu$ is the mobility of the screw dislocation, $b$ is the magnitude of Burgers vector and $\tau$ is the dislocation velocity. At high temperatures, the grown-in dislocation density in Nb is roughly $10^{10}$/m$^2$ [54]. However, the mobile dislocation density leading to localized slip should be much lower than this. For example, if we consider a typical grain in the bulk sample (the average grain size in our experiment is $\sim 70$ $\mu$m) subjected to localized slip, i.e., a constantly operating dislocation source (e.g., Frank-Read source) emitting one mobile dislocation each time to glide across the grain, then the mobile dislocation density is estimated to be on the order of $10^3$/m$^2$. Using this estimated mobile dislocation density and the dislocation velocity ($10^{-1}$ m/s) at 0.3 GPa in MD simulation, we get a strain rate on the order of $10^{-3}$ s$^{-1}$, similar to that used in our experiments. This suggests that at a strain rate comparable to that in typical lab experiments, the random force field still significantly enhances the cross-kink and point defect formation. Second, strong interactions between light solutes and SD are common in BCC metals. The resultant random force field of either repulsive (see Fig. S13 for the calculations on other group V BCC metals) or attractive type [55] would significantly enhance cross-kink and point defect generation. Third, it is also commonplace in BCC metals for light elements to stabilize vacancies [56,57]. As these are the key factors involved

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Fig. 8. Damage accumulation to form nano-cavities. (a) A SD is forming a vacancy pinning site (purple atoms). (b) The SD drags out a long V-O tube after the 1st pass of SD. (c) The V-O tube becomes larger as subsequent SDs continue to drag out vacancies on the existing vacancy tube. (d) The size of the V-O tube is significantly increased after six passes of SDs. (e) After nine passes of SDs, more V-O clusters are formed while the existing nano-cavities become even larger. (f) The cross section indicated by the pair of dashed lines on the reader is referred to the Web version of this article.) (g) The structure of a V-O cluster highlighted by the rectangle in (e). (For interpretation of the references to color in this figure legend, the
in the presented hardening and damage initiation mechanism, the mechanism should be widely active in BCC metals.

5. Conclusion

We have demonstrated and analyzed an example of the general triangular relationship between mobile impurity species, plasticity and damage. This interplay leads to fast hardening and embrittlement of Nb, as seen in our experiments. Our MD simulations reveal that under the repulsive force field due to O solutes, the screw dislocation emits vacancy clusters and interstitial clusters much like in primary radiation damage. O stabilization suppresses the decomposition of vacancies into kinks by passing screw dislocations. The dynamic formation of copious stabilized V-O complexes during plastic deformation strongly obstructs the movement of screw dislocations to cause marked hardening. Meanwhile the ‘delayed pinch-off’ of cross-kinks accumulate vacancies, which are further stabilized by O interstitials, to instigate damage, and the nano-cavities coalesce to cause failure. While our model case is O in Nb, the defect mechanisms uncovered are likely to be relevant not only to O-embrittlement but also to generic damage problems including irradiation and H-embrittlement, when screw dislocations are important for plasticity such as in BCC materials.

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